

Learning efficient, task-dependent representations with synaptic plasticity

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Motivation

- Neural circuits cannot perfectly represent the sensory world: their capacity is limited by the number of neurons, response variability (noise) lacksquareand various biophysical constraints [1].
- These limited resources should be allocated to represent the stimuli that matter, either because they are frequent or critical for obtaining reward. ullet
- Can a recurrent neural network achieve this goal with simple, biologically plausible synaptic plasticity rules [2]? \bullet



Stochastic nonlinear network dynamics (rate-based):

$$dr_{i} = \left[-\frac{f^{-1}(r_{i})}{R} + \sum_{j=1}^{N} w_{ij}r_{j} + \sum_{k=1}^{d_{s}} c_{ij}s_{j}(\theta) + b_{i} \right] dt + \sigma dB_{i}$$

Energy [4]:

$$E = -\frac{1}{2} \sum_{i,j} w_{ij} r_i r_j + \sum_i \frac{1}{R} \int_0^{r_i} f^{-1}(r_i) dr_i - \sum_{ij} c_{ij} s_j r_i - \sum_i b_i r_j$$
$$p(\mathbf{r}|\mathbf{s}(\theta), \mathbf{W}) = \frac{1}{Z} e^{-\frac{E(\mathbf{r};\mathbf{s},\mathbf{W})}{\sigma^2}}$$

Deriving a synaptic plasticity rule

 $\Delta w_{ij} \propto \frac{\partial}{\partial w_{ij}} \mathcal{O}(\mathbf{D}, \mathbf{W})$

by stochastic gradient ascent:

Optimize a task-specific objective function:

accuracy

$$\mathcal{O}(\mathbf{D}, \mathbf{W}) = \int \alpha(\mathbf{Dr}, \mathbf{s}) p(\mathbf{r} | \mathbf{s}(\theta), \mathbf{W}) p(\theta) d\mathbf{r} d\theta - \lambda \|\mathbf{W}\|_2$$

metabolic constraints

giving a synaptic update:

$$\Delta w_{ij} \propto \alpha (\mathbf{Dr}, \mathbf{s}) \left(r_i r_j - \langle r_i r_j \rangle_{p(\mathbf{r}|\mathbf{s})} \right) - \lambda w_{ij}$$

*Similar local update rules for C, b, D

Prior statistics and internal noise Learning task-specific representations learning peak tuning sharp prior learning peak tuning 0.4 0.4 -0.2 -0.5 0.22 **Frequency** duency racy accuracy avg do aci -1.0 -3.0 1000 1000 0.12 0.0 250k 250k 0 -Π Π -Π Т -Π time time Learned tuning curves tend to cluster in task-relevant regions of the stimulus space Networks show reduced firing and decreased performance for unlikely stimuli. ratio 0.3 d' = 2.51 .35 d' = 1 high low (|WSE |) bo -2.0 prob prob input bias 3.0 density 2.0 variance ecurrent 1.0 0.0 test stim. -π Π 0.08 0.08 250k -0.08 -0.08 OW time estimate decoder axis decoder axis noise noise

The network performs better for more probable stimuli in both tasks

Networks with higher noise learn to emphasize recurrent connectivity, and develop noise compensation mechanisms

high

Conclusions

- We derive local plasticity rules that optimize task-specific cost functions, under resource constraints (internal noise and metabolic limitations).
- The model takes advantage of intrinsic network noise to perform stochastic gradient ascent on task objective functions.
- The circuit learns to exploit natural input statistics by concentrating neural resources around frequent stimuli, with a corresponding improvement in performance.
- Future work: time-dependence [3], unsupervised learning, simultaneously learning several tasks.

References

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